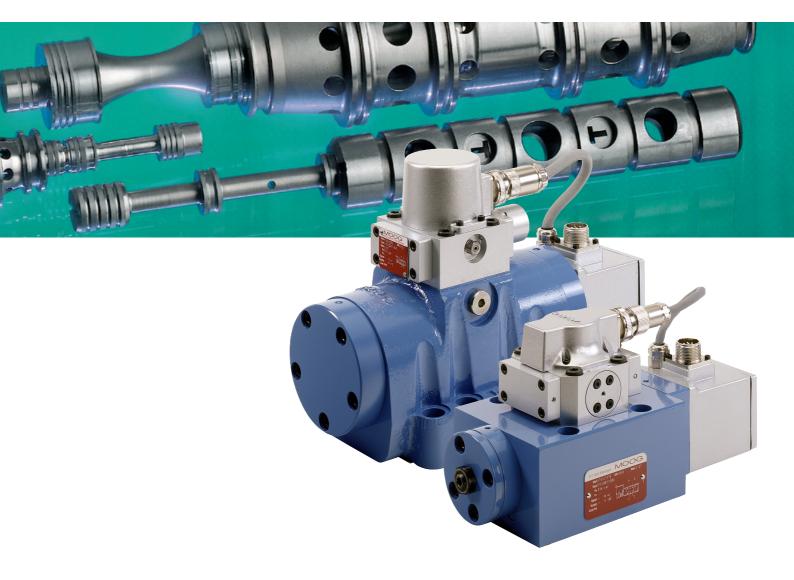


Servovalves with integrated Electronics D791 and D792 Series



The flow control servovalves D791 and D792 Series are throttle valves for 3-way and preferably 4-way applications. These three stage servovalves have been especially developed for such demanding applications where high flow rates and at the same time extreme dynamic performance requirements must be met. The design of these valves is based on the well known D079 Series. The integrated electronics has been replaced by a new design applying SMD technology. The valves are offered with pilot valves of D761 or D765 Series, optional standard response or high response versions are available. Series D791 can deliver rated flow up to 250 l/min, Series D792 is available with rated flow up to 1000 l/min.

These valves are suitable for pressure or force control, position and velocity control systems with high dynamic response requirements.

Principle of operation

An electrical command signal (set point, input signal) is applied to the integrated control amplifier which drives a current through the pilot valve coils. The pilot valve produces differential pressure in its control ports. This pressure difference results in a pilot flow which causes main spool displacement.

The position transducer which is excited via an oscillator measures the position of the main spool (actual value, position voltage). This signal then is demodulated and fed back to the control amplifier where it is compared with the command signal. The control amplifier drives the pilot valve until the error between command signal and feedback signal is zero. Thus, the position of the main spool is proportional to the electrical command signal.

The valves D791 and D792 Series described in this catalogue have successfully passed EMC tests

required by EC Directive. Please

take notice of the respective

references in the electronics

section.

CE

Operational features

- Electrical position feedback with pressure isolated position transducer (LVDT), no wear
- □ Integrated SMD electronics with false polarity protection
- Optional external pilot supply and return connections via fifth and sixth port in valve body
- Low threshold and hysteresis, excellent null stability
- Preadjusted at factory

The actual flow depends on the electrical command signal and the valve pressure drop, and may be calculated using the square root function for a sharp-edged orifice.

The flow value Q calculated in this way should not exceed an average flow velocity of 30 m/s in ports P, A, B and T.

$$Q = Q_N \sqrt{\frac{\Delta p}{\Delta p_N}}$$

Q [l/min] = calculated flow Q_{N} [l/min] = rated flow

 Δp [bar] = actual valve pressure drop

 Δp_{N} [bar] = rated valve pressure drop

If large flow rates with high valve pressure drops are required, an appropriate higher pilot pressure has to be chosen to overcome the flow forces. An approximate value can be calculated as follows: $p_{\chi} \ge 2.5 \cdot 10^{-2} \cdot \frac{Q}{A_{\kappa}} \sqrt{\Delta p}$

Q [l/min] = max. flow

 Δp [bar] = valve pressure drop with Q

 A_{κ} [cm²] = spool drive area

 p_{x} [bar] = pilot pressure

The pilot pressure p_x has to be at least 15 bar above the return pressure of the pilot stage.

Our quality management system is certified in accordance with DIN EN ISO 9001.



This catalogue is for users with technical knowledge. To ensure that all necessary characteristics for function and safety of the system are given, the user has to check the suitability of the products described here. In case of doubt please contact Moog.

D791 and D792 Series General technical data

MOOG

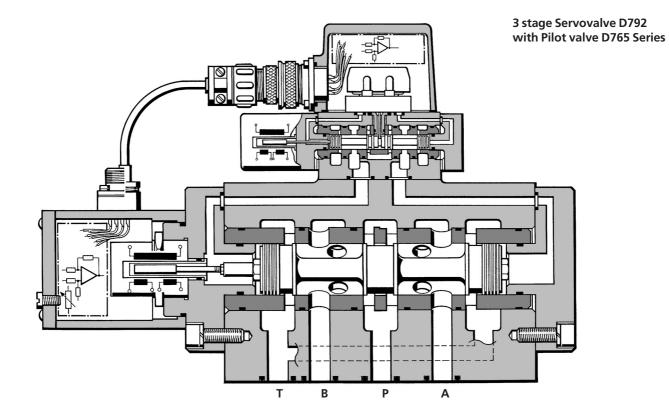
ping plate

Operating pressure range		Recommended cleanliness class	
Main stage		for normal operation:	ISO 4406 < 17/14/11
Ports P, A and B		for longer life:	ISO 4406 < 16/13/10
with X internal	up to 315 bar	System filtration	
with X external	up to 350 bar	Pilot valve:	High pressure filter (without by-
Port T with Y internal	up to 210 bar		pass, but with dirt alarm) mounted
Port T with Y external	up to 350 bar		in the mainflow and if possible,
			directly upstream of the servo-
Pilot valve			valve.
Ports P, A and B		Main stage:	Main stage: high pressure filter as
D761, D765 Series	up to 315 bar		for the pilot stage. In combination
Port T	up to 210 bar		with a fast regulating VD-pump a
Temperature range			bypass filter is possible.
Ambient	-20 to +60 °C	Filter rating recommended	
Fluid	-20 to +80 °C	for normal operation:	$\beta_{10} \ge 75 (10 \ \mu m \ absolute)$
Seal material	FPM, others on request	for longer life:	$\beta_5 \ge 75$ (5 µm absolute)
Operating fluid	Mineral oil based hydraulic fluid	Installation options	any position, fixed or movable
	(to DIN 51524), others on request	Vibration	30 g, 3 axes
Viscosity	recommended 15 to 100 mm ² /s	Degree of protection	EN 60529: IP 65 (with mating con-
Class of cleanliness	The cleanliness of the hydraulic		nector mounted)
	fluid greatly effects the per-	Shipping plate	Delivered with an oil sealed ship-
	C / I ''' ' I''		

formance (spool positioning, high

resolution) and wear (metering edges, pressure gain, leakage) of

the valve.



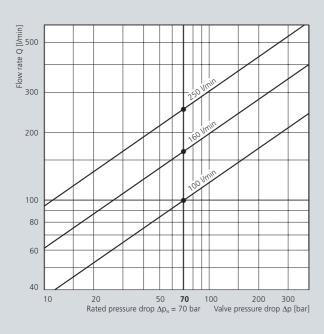
D791 Series Technical data

ModelType				D791 S	
Mounting pattern	ISO, but X and Y do n o pond to ISO	ot corres-		ISO 10372-06-05-0-9	02
Valve body version				4-way	
Pilot valve		with bushing spool optional D761 or D7			
Pilot connection	optional, internal or e	xternal		X and Y	
Mass		[kg]		13	
Rated flow	$(\pm 10\%)$ at $\Delta p_N = 35$ k	bar			
	per land	[l/min]	100	160	250
Response time*	for 0 to 100% stroke	(depen-			
	dent on pilot valve)	[ms]		3 to 10	
Threshold*		[%]		< 0,2	
Hysteresis*		[%]		< 0,5	
Null shift	with $\Delta T = 55 \text{ K}$	[%]		< 2	
Null leakage flow*	total, max.	[l/min]	5	7	10
Pilot leakage flow*	max., for 100% step in	put (de-			
	pendent on pilot valve)	[l/min]		4 to 11	
Main spool stroke		[mm]	1,4	1,2	2,0
Main spool drive area		[cm ²]		2,85	

* measured at 210 bar pilot or operating pressure, fluid viscosity of 32 mm²/s and fluid temperature of 40 °C

Typical characteristic curves measured at 210 bar pilot or operating pressure, fluid viscosity of 32 mm²/s and fluid temperature of 40 °C

Valve flow diagram



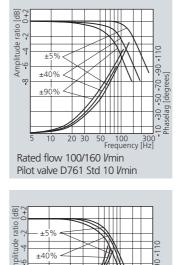
Valve flow for maximum valve opening (100% command signal) as a function of the valve pressure drop

Frequency response

for valves with different rated flows and different pilot valves

-10 Pha

20 30 50 100 300 Frequency [Hz]



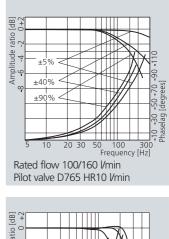
±90% -

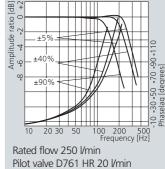
10

Rated flow 250 l/min

Pilot valve D761 Std10 l/min

5





D792 Series Technical data

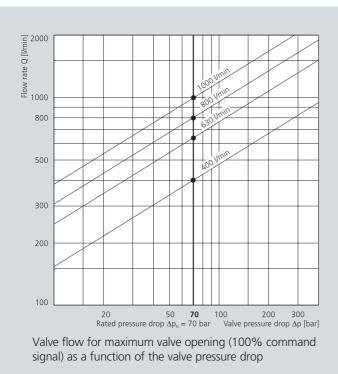
MOOG

Model Type Mounting pattern Valve body version	punting pattern					D792 S Moog Standard 4-way 3-stage with bushing spool assembly				
Pilot valve				2-stage, op	tional D761 or	D/65 Seri	es			
Pilot connection	optional, internal or ex	kternal			X and Y					
Mass		[kg]			17					
Rated flow	$(\pm 10\%)$ at $\Delta p_{N} = 35$ b	ar								
	per land	[l/min]	400	630		800	1000			
Response time*	for 0 to 100% stroke	(depen-								
	dent on pilot valve)	[ms]			4 to 12					
Threshold*	•	[%]			< 0,2					
Hysteresis*		[%]			< 0,5					
Null shift	with Δ T = 55 K	[%]			< 2					
Null leakage flow*	total, max.	[l/min]	10	14		14	14			
Pilot leakage flow*	max., for 100% step in	put (de-								
5	pendent on pilot valve)	•			6 to 16					
Main spool stroke		[mm]	1,8	1,9		2,6	4,0			
Main spool drive area		[cm ²]	3,8	7,14		7,14	7,14			
Main spool unve area		[CIII-]	5,0	7,14		7,14	7,14			

* measured at 210 bar pilot or operating pressure, fluid viscosity of 32 mm²/s and fluid temperature of 40 °C

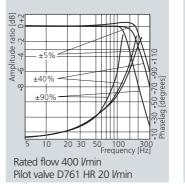
Typical characteristic curves measured at 210 bar pilot or operating pressure, fluid viscosity of 32 mm²/s and fluid temperature of 40 °C

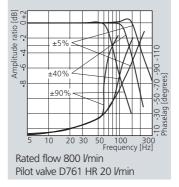
Valve flow diagram

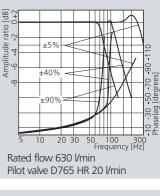


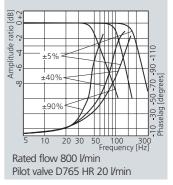
Frequency response

for valves with different rated flows and different pilot valves

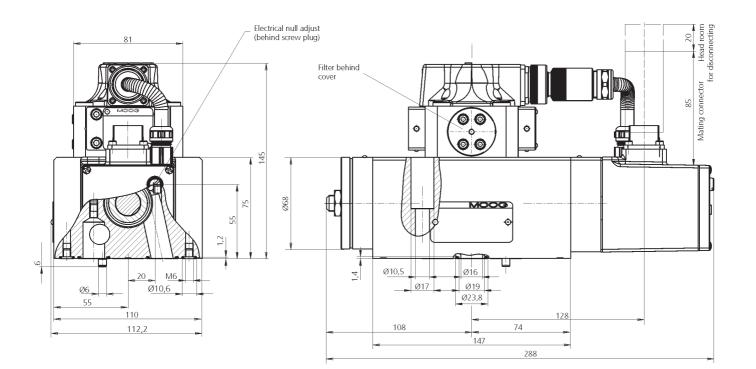








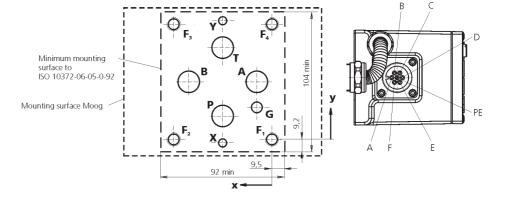
D791 Series Installation drawing with Pilot valve D761 Series Conversion instruction



The mounting manifold must conform to ISO 10372-06-05-0-92.

Note: The X port to ISO Standard must **not** be machined. The X and Y ports of Moog valve body do **not** correspond to ISO Standard.

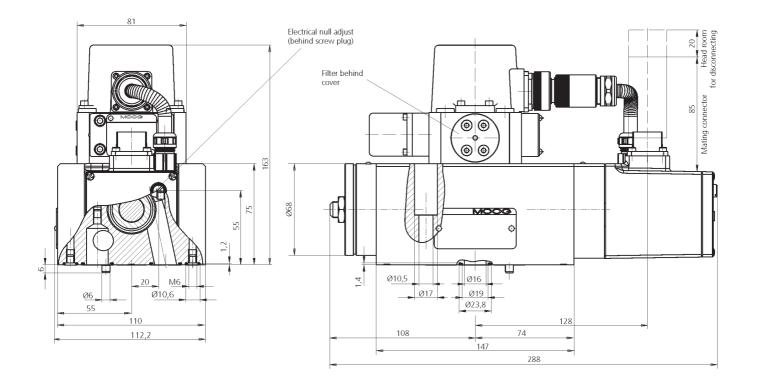
Mounting surface needs to be flat within 0,02 mm. Average surface finish value, Ra, better than 1μ m.

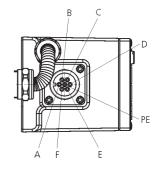


	Р	Α	В	Т	G	Х	Y	F1	F2	F3	F4
	Ø16	Ø16	Ø16	Ø16	Ø8	Ø6	Ø6	M10	M10	M10	M10
х	36,5	11,1	61,9	36,5	11,1	36,5	36,5	0	73	73	0
У	17,4	42,8	42,8	68,2	23,7	-2,6	88,2	0	0	85,6	85,6

D791 Series Installation drawing with Pilot valve D765 Series Spare parts, Accessories



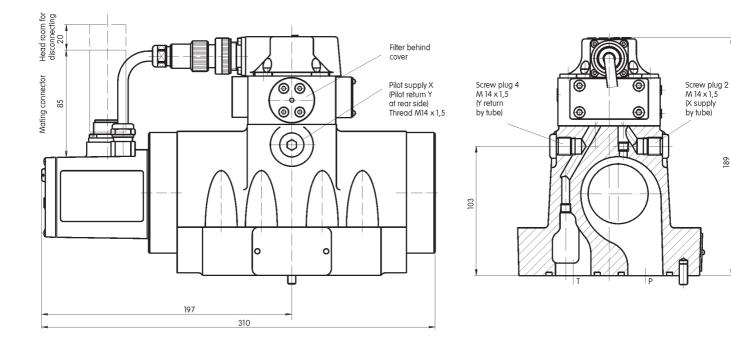




Spare parts and accessories for D791 Series

O-rings (included in delivery)			FPM 85 Shore
for P, T, A, B	4 pieces	ID 20,3 x 1,78	as service seal set
for X, Y	2 pieces	ID 7,65 x 1,78	B97215-V791-22
Mating connector, waterproof IP 6	5 (not included in delivery)	for cable dia	
6+PE-pole DIN 43563		min. Ø 10 mm, max. Ø 12 mm	B97007 061
Flushing plate (internal supply)			55118 001
(external supply)			A26133
Mounting bolts (not included in de	elivery)		
M 10 x 50 DIN 912-10.9	4 pieces	required torque 65 Nm	A03665 100 050
Replaceable filter for pilot valve		65 µm nominal	A67999 065
O-rings for filter replacement and Service seal set	pilot valve 1 piece		FPM 85 Shore B97215-V761F76

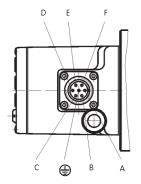
D792 Series Installation drawing with Pilot valve D761 Series Conversion instruction

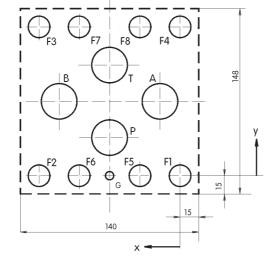


Note: The X and Y tubes have to be connected to the Moog valve body by fittings. Mounting surface needs to be flat

within 0,02 mm. Average surface finish value, Ra, better than $1\mu m.$

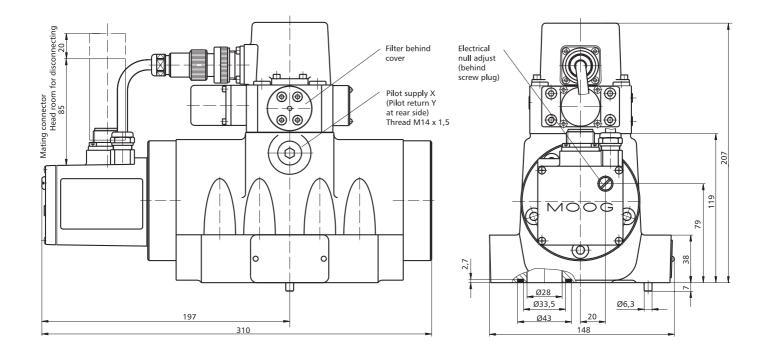
	Р	Α	В	Т	G	F1	F2	F3	F4	F5	F6	F7	F8
	Ø28	Ø28	Ø28	Ø28	Ø8	M16	M16	M16	M16	M16	M16	M16	M16
х	55,4	15,8	95,0	55,4	55,4	0	110,8	110,8	0	31,5	79,3	79,3	31,5
У	30,1	58,7	58,7	87,3	0	0	0	117,4	117,4	0	0	117,4	117,4

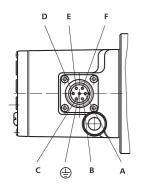




D792 Series Installation drawing with Pilot valve D765 Series Spare parts, Accessories







Spare parts and accessories for D792 Series

O-rings (included in delivery) for P, T, A, B	4 pieces	ID 36 x 3,5	FPM 85 Shore as service seal set B97215-V792-22
Mating connector, waterproof IP 65 (no 6+PE-pole DIN 43563	ot included in delivery)	for cable dia min. Ø 10 mm, max. Ø 12 mm	P07007 061
Flushing plate		11111. Ø 10 11111, 111dX. Ø 12 11111	76216 001
Mounting bolts (not included in delivery) M 16 x 60 DIN 912-10.9	required 8 pieces	required torque 290 Nm	A03665 160 060
Replaceable filter for pilot valve		65 µm nominale	A67999 065
O-rings for filter replacement and pilot Service seal set	valve 1 piece		FPM 85 Shore B97215-V761F76

Command signal 0 to ±10 V Valves with voltage command input

The spool stroke of the valve is proportional to $(U_{\rm D} - U_{\rm E})$. 100% valve opening P \blacklozenge A and B \blacklozenge T is achieved at $(U_{\rm D} - U_{\rm E}) = +10$ V. At 0 V command the spool is in a centred position.

The input stage is a differential amplifier. If only one command signal is available, pin D or E is connected to signal ground \perp (pin C) according to the required operating direction (to be done at the mating connector).

Command signal 0 to ±10 mA Valves with current command input

The spool stroke of the valve is proportional to $(I_D - I_E)$. 100% valve opening P \blacklozenge A and B \blacklozenge T is achieved at $(I_D - I_E) = +10$ mA. At 0 mA command the spool is in a centred position.

Either pin D or E is used according to the required operating direction. The unused pin is left open (not connected at the mating connector). The input pins D and E are inverting.

Actual value 0 to ±10 V Valves with voltage command input

The actual spool position value can be measured at pin F. This signal can be used for monitoring and fault detection purposes. The spool stroke range corresponds to ± 10 V. 100% valve opening P \blacklozenge A and B \blacklozenge T corresponds to ± 10 V.

Actual value 0 to ± 10 mA or 4 to 20 mA

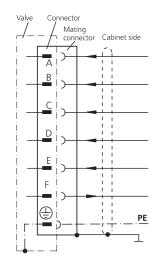
Valves with current command input

The actual spool position value can be measured at pin F. This signal can be used for monitoring and fault detection purposes. The spool stroke range corresponds to $\pm 10 \text{ mA}$ (4 to 20 mA). 100% valve opening P \blacklozenge A and B \blacklozenge T corresponds to $\pm 10 \text{ mA}$ (20 mA).

General requirements

- Supply ± 15 VDC ± 3%. Ripple <50 mV_{pp}. Current consumption max. ± 250 mA
- 🗖 All signal lines, also those of external transducers, shielded
- \Box Shielding connected radially to \perp (0V), power supply side, and connected to the mating connector housing (EMC)
- EMC: Meets the requirements of EN 55011/03.91 class B, EN 50081-1/01.92, and EN 50082-2/03.95, performance criterion class A
- **Protective grounding lead** \geq 0,75mm²
- ☐ Note: When making electrical connections to the valve (shield, protective grounding) appropriate measures must be taken to ensure that locally different earth potentials do not result in excessive ground currents. See also Moog Application Note AM 353 E.

Wiring for valves with 6+PE pole connector to DIN 43563 and mating connector (metal shell) with leading protective grounding connection ($_{\pm}$).



Function	Current command	Voltage command
Supply	+ 15 VDC ± 3	
Supply	– 15 VDC ± 3	
Supply / signal ground	上 (0V)	
Input rated command Valve flow	0 to \pm 10 mA Load resistance (diff.) 1 k Ω	0 to \pm 10 V Input resistance 10 k Ω
Input rated command (differential) Valve flow	$ \begin{array}{l} \mbox{Input command} & \mbox{I}_{\rm D} = -\mbox{I}_{\rm E}^{:} \mbox{0 to } \pm 10 \mbox{ mA} \\ \mbox{Input command (inverted)} & \mbox{I}_{\rm E} = -\mbox{I}_{\rm D}^{:} \mbox{0 to } \pm 10 \mbox{ mA} \\ \mbox{Input voltage for } U_{\rm D-B} \mbox{ and } U_{\rm E-B} \mbox{ for both signal types is limited to } \end{array} $	$U_{D-E} = 0 \text{ to } \pm 10 \text{ V}$ ($R_{e} = 10 \text{ k}\Omega$) min15 V and max. +32 V
Output actual value Main spool position	0 to \pm 10 mA Load resistance max. 500 Ω	0 to \pm 10 V Output resistance 50 Ω
Protective grounding		

D791 and D792 Series Valve electronics with supply voltage 24 Volt

Command signal 0 to ±10 mA floating, Valves with

current command input

The spool stroke of the valve is proportional to $I_p = -I_e$. 100 % valve opening P \blacktriangleright A and P \doteq T is achieved at $I_p = +10$ mA

B \blacklozenge T is achieved at I_D = +10 mA. At 0 mA command the spool is in centred position.

The input pins D and E are inverting. Either pin D or E is used according to the required operating direction. The other pin is connected to signal ground at cabinet side.

Command signal 0 to ± 10 V, Valves with

voltage command input The spool stroke of the valve is

proportional to $(U_p - U_e)$. 100 % valve opening P \blacklozenge A and B \blacklozenge T is achieved at $(U_p - U_e) = +10$ V. At 0 V command the spool is in centred position.

The input stage is a differential amplifier. If only one command signal is available, pin D or E is connected to signal ground at cabinet side, according to the required operating direction.

Actual value 4 to 20 mA

The actual spool position value can be measured at pin F (see diagram below). This signal can be used for monitoring and fault detection purposes.

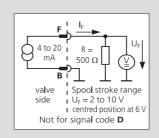
The spool stroke range corresponds to 4 to 20 mA. The centred position is at 12 mA. 20 mA corresponds to 100 % valve opening $P \blacklozenge A$ and $B \blacklozenge T$. The position signal output 4 to 20 mA allows to detect a cable break when $I_c = 0$ mA.

For failure detection purposes it is advised to connect pin F of the mating connector and route this signal to the control cabinet.

General requirements

- Supply 24 VDC, min. 18 VDC, max. 32 VDC Current consumption max. 300 mA
- All signal lines, also those of external transducers, shielded.
- Shielding connected radially to \perp (0 V), power supply side, and connected to the mating connector housing (EMC).
- **EMC**: Meets the requirements of EN 55011:1998, class B, EN 50082-2:1995, performance criterion class A.
- ☐ Minimum cross-section of all leads \ge 0,75 mm². Consider voltage losses between cabinet and valve.
- Note: When making electric connections to the valve (shield, protective earth) appropriate measures must be taken to ensure that locally different earth potentials do not result in excessive ground currents. See also Moog Application Note AM 353 E.

Circuit diagram for measurement of actual value I_F (position of main spool)



Note: Enable input

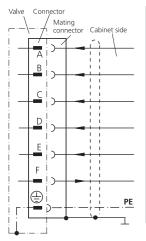
With enable signal off, the main spool will move to a safe position. a) Centred position (unbiased pilot valve)

function code **A**¹) b) End position (biased pilot valve) function code **B**¹)

¹) see type designation

Wiring for valves with 6+PE pole connector

to EN 175201 Part 804 ²), and mating connector (type R and S , metal shell) with leading protective earth connection (\pm). See also wiring instructions AM 426 E.



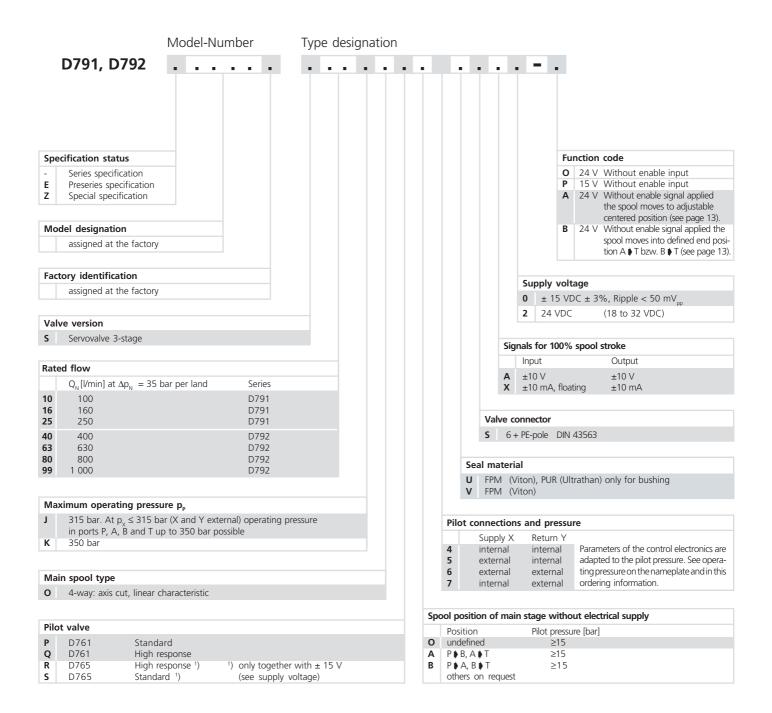
Function	Current command	Voltage command				
Supply	24 VDC (min. 18 VDC, max. 32 VDC). I _{max} =	24 VDC (min. 18 VDC, max. 32 VDC). I _{max} = 300 mA				
Supply / Signal ground	⊥ (0 V)					
Enabled Not enabled	$U_{c^{-B}}$ > +8,5 VDC I_{e} = 2,0 mA at 24 VDC (see	note above)				
Input rated command (differential)	$ \begin{array}{llllllllllllllllllllllllllllllllllll$	$U_{D-E} = 0 \text{ to } \pm 10 \text{ V}$ ($R_e^{} = 10 \text{ k}\Omega$) n. –15 V and max. +32 V				
Output actual value spool position	I_{F-B} = 4 to 20 mA. At 12 mA spool is in centred position. R_L = 10 Signal code D (see page 7): U_{F-B} = 2 to 10 V. At 6 V spool is in centre					
Protective earth						

²) formerly DIN 43563

Notes

D791 und D792 Series Ordering information



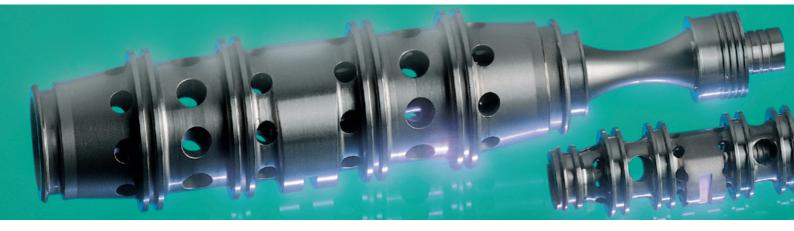


Preferred configurations are highlighted. All combinations may not be available. Options may increase price. Technical changes are reserved.

MOOG



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